Take top chassis plate. It has a lot of holes to mount Intel NUCs, Nvidia Jetson (Auvidea Version), Raspberry PI, LattePanda, and AAEON UP Xtreme i11 boards.

Also, it has holes to mount Realsense camera in front and rear part of the robot, so you can have Visual SLAM using two Realsense cameras.



Place it on the standoffs by aligning motor mount studs with the rectangular slots on the top plate.



Side view.



Now fix it using four M2.5x10 mm screws.

