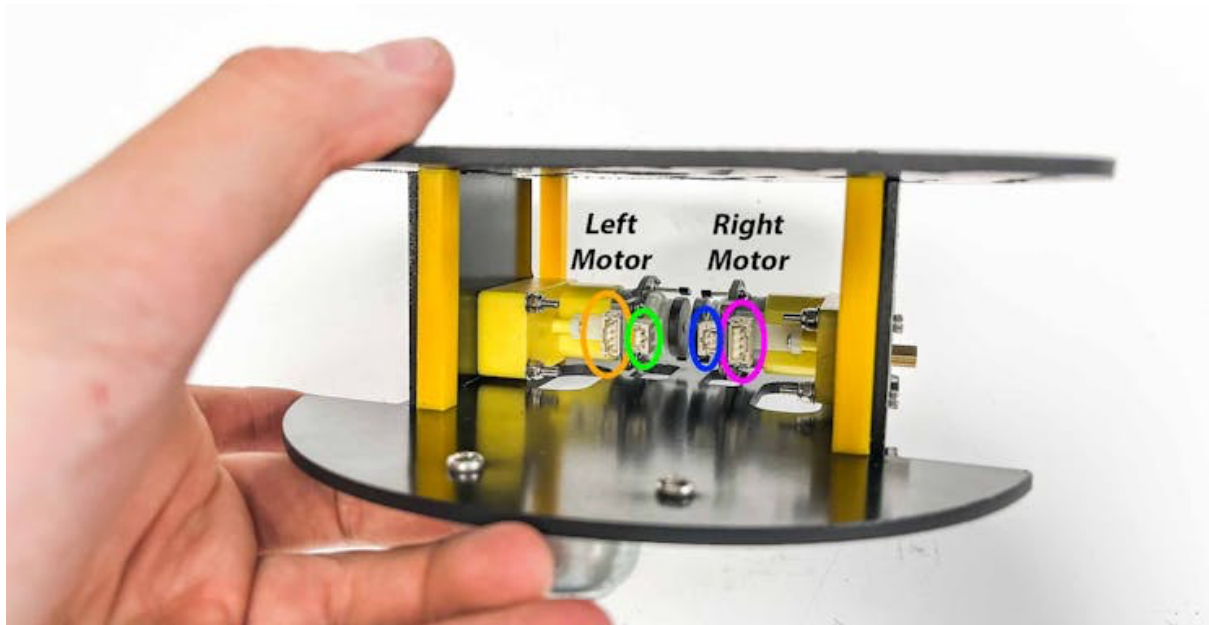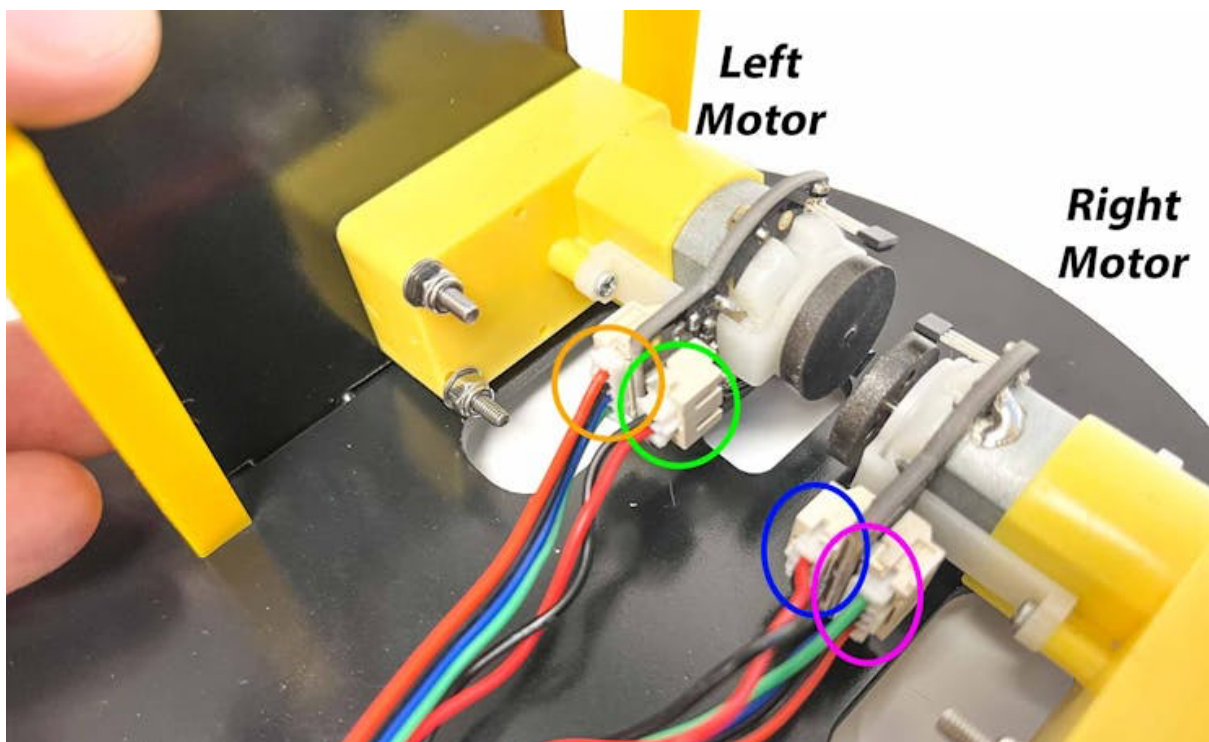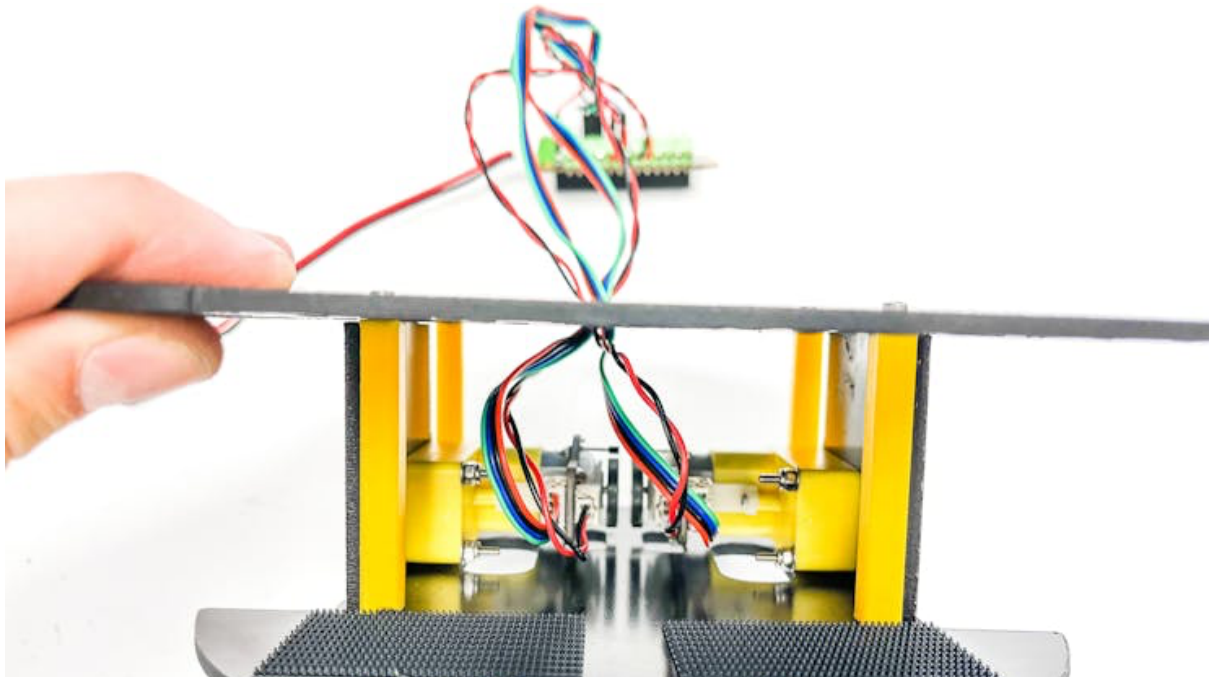After that connect wires to the correct motors. Left motor wires connect to the left motor, and its encoder. Do the same for right motor.

Connect wires

How it will look like

You might use plastic tube to do wiring more accurate.