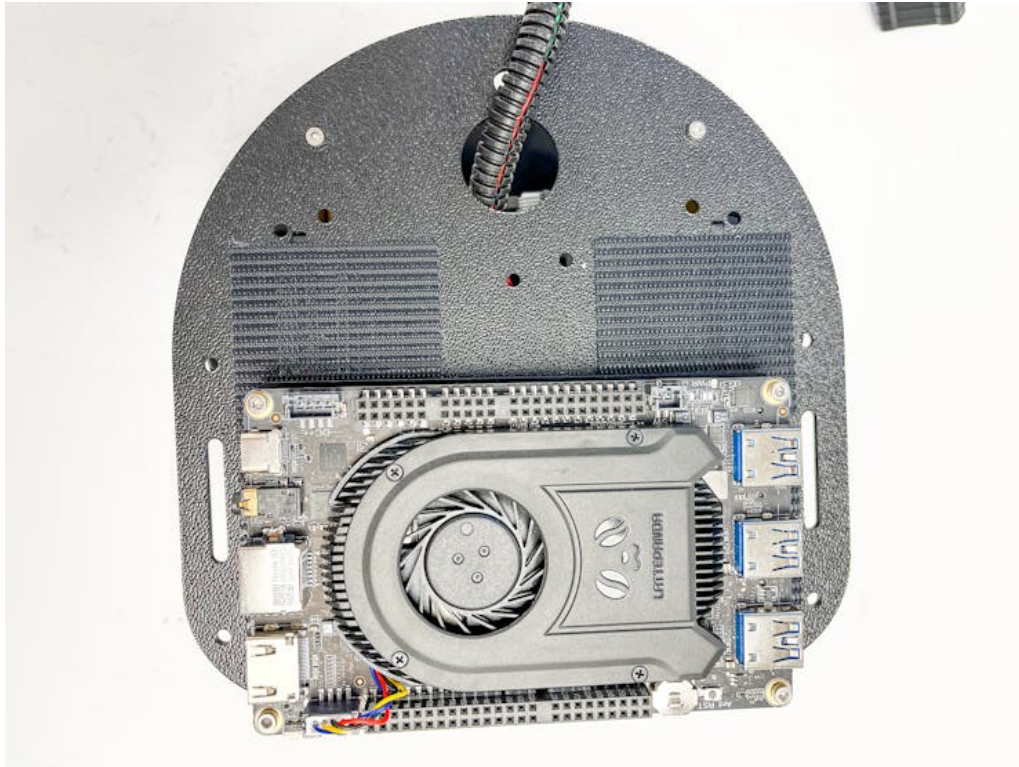
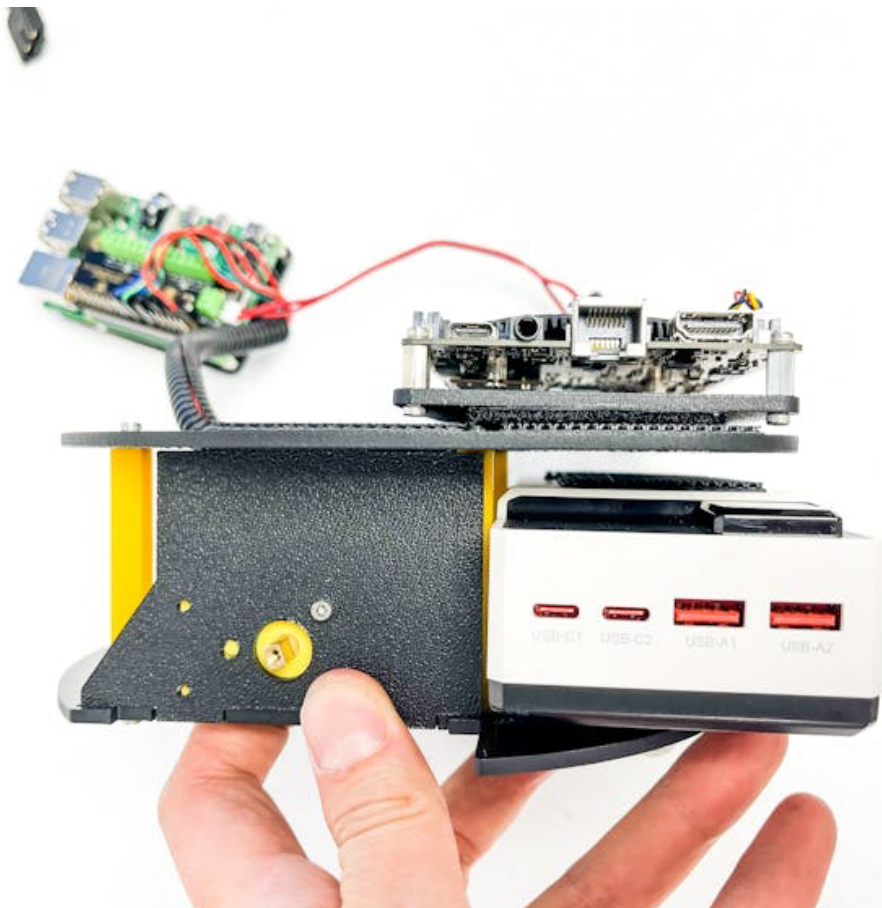


Now, install the LattePanda board as shown. Keep in mind that the placement of electronics may vary depending on your robot model. Use the photos below as a general reference.



Next goes power bank.





After that install Li-Po batter on top.

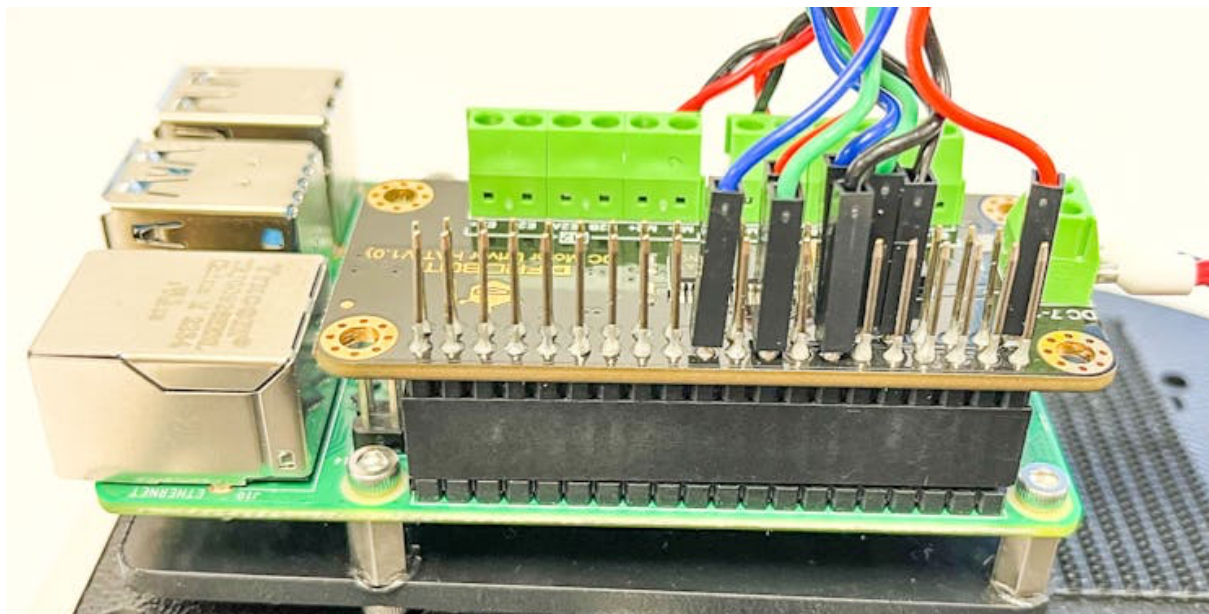




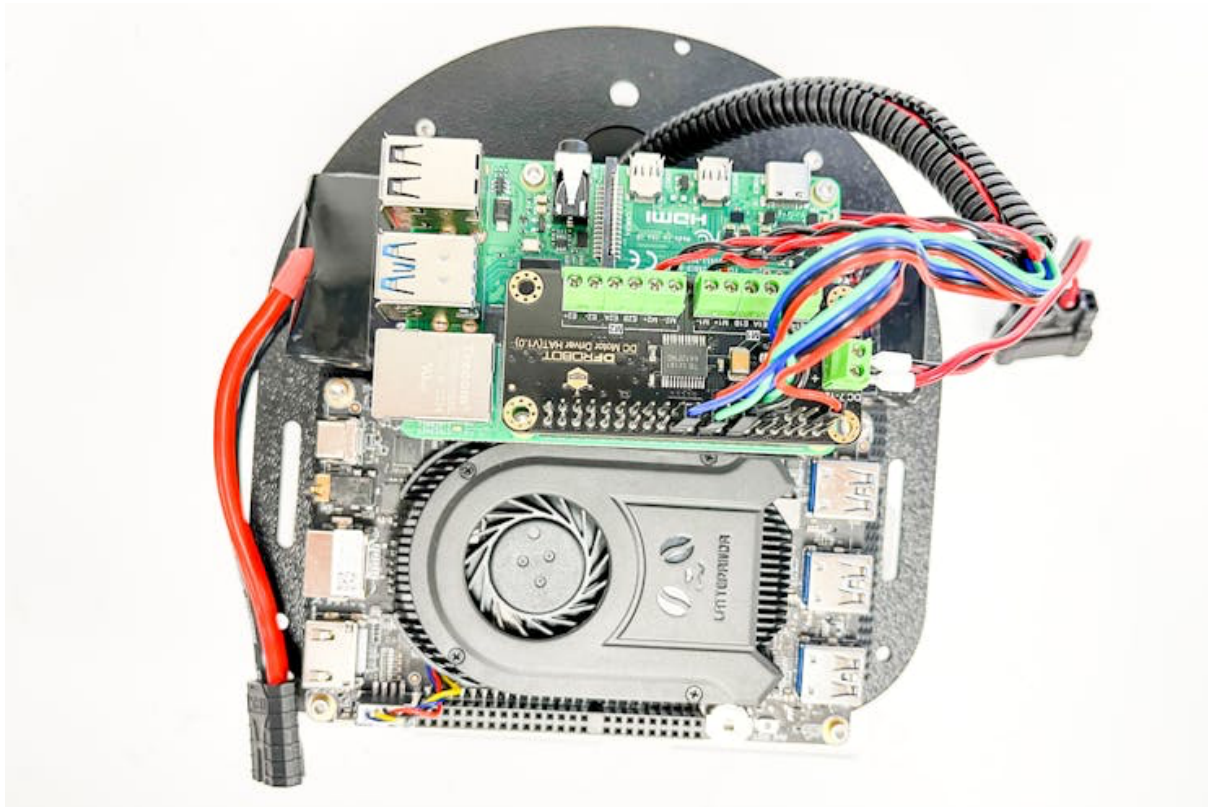
Battery after installation.



Connect Raspberry PI with HAT Motor Driver.



And now stick Raspberry on top of the Li-Po battery.



Side view.

